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ACCELEROGRAPH STATIONS SITE CHARACTERIZATION USING AMBIENT NOISE: SELECTED STATIONS IN GREECE

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ABSTRACT – Recent research efforts showed that ambient noise measurements performed either by a single autonomous station or by an array configuration can be used along with a proper methodology to satisfactorily acquire the shear wave velocity profile at a site. The knowledge of shear wave velocity of the subsurface structure at strong motion stations is indispensable since it can significantly optimize the use of existing and future strong motion recordings obtained, rendering them usable to their full potential. Microtremor array measurements have been acquired in six strong motion sites of the national strong motion network in Greece where shear wave velocity information exist at least up to a depth of about 40 m. In two sites, borehole and cross-hole data show the depth of the seismic bedrock. The array geometry used consists of three co-central circles in each site at different apertures. Data have been processed using both F-K and SPAC methods and an inversion of the resulted dispersion curve and auto-correlation data has been followed, respectively. The resulted models are compared with shear wave velocity models from other geophysical methods and the reliability and accuracy of the array method has been evaluated.

1. Introduction

The quantitative assessment of site effects, that is the ground motion effects associated with the local surface geology (among others Borchardt, 1970; Campell, 1976), is a major issue in engineering seismology studies. Impact and resonance effects of S-waves within unconsolidated sediments overlaying stiffer formations cause frequency dependent site amplifications. Thus, it is of key interest to determine the shallow shear wave velocity structure (Hartzell et al. 1996, Yamanaka 1998). In recent years, the passive recording of microtremors at single stations (among others Bard, 1998; Ishida et al., 1998; Fäh et al., 2003; Arai and Tokimatsu, 2004) or at small-scale arrays (among others Tokimatsu 1997, Scherbaum et al. 2003) has gained considerable attention for the determination of shallow shear wave velocity profiles. The major advantages of these ambient vibration techniques are the low cost exploration and monitoring capabilities, the possibility to perform non-destructive measurements at every place of a densely populated city, and the relatively large penetration depth.

In the present study we apply the array microtremor method in six strong motion sites that in five of them we have earthquake recordings and in all of them we have additional geophysical information from Cross-Hole (CH) data (Pitilakis, 1996; Athanassopoulos et al., 1999; Anastasiadis et al., 2003; Anastasiadis, 2004; Dimitriou et al., 2004). We try to correlate the shear wave velocity, the depth of the first layer and the bedrock calculated from the array data with these calculated from CH data (D_{CH}). Additionally we compare the depth of the bedrock as this is calculated from the resonance frequency from ambient noise recordings (H/V) $D_{HVnoise}$, earthquake data (H/V) D_{HVeq} , and the array data, D_{array} , in order to check the validity of the microtremor array method.

2. Data Used

Microtremor array data were collected at six strong motion sites of the permanent National Strong Motion Network in Greece. The sites used are presented in Figure 1. Three of them correspond to D soil category based on NHERP 1997 (Lefkas/LEF1, Pirgos/PIR1, Korinthos/KOR1) and three of them correspond to C soil category (Patra/PAT2, Vartholomio/VAR1, Aigion/AIG1).

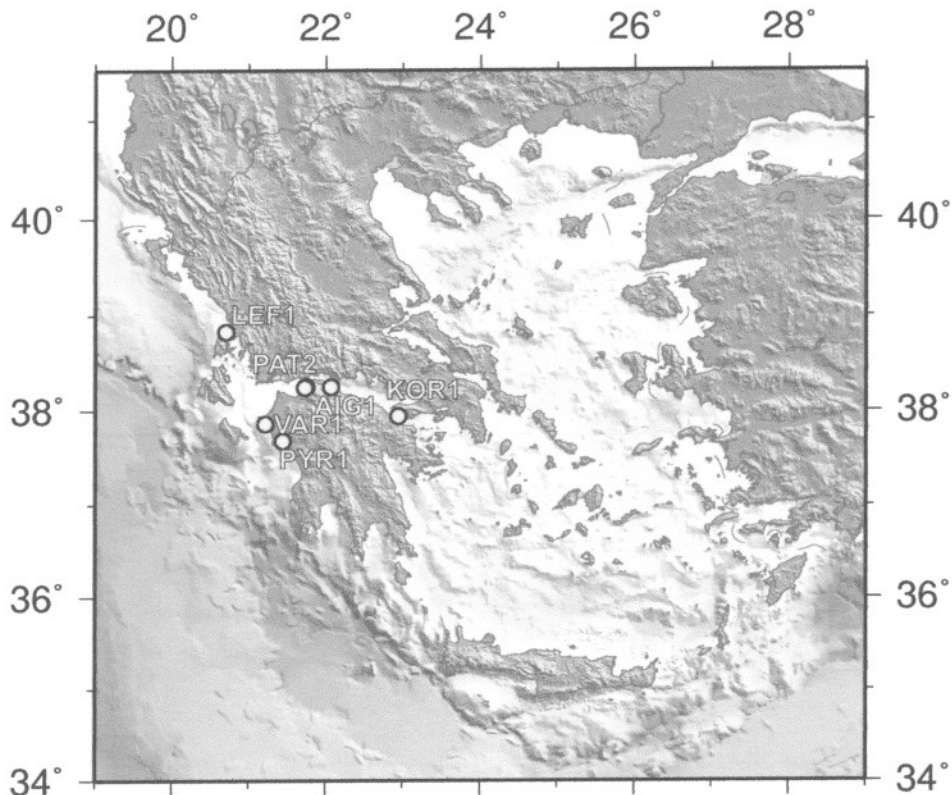


Figure 1. Map of Greece where the sites used during this study are presented.

For the array recordings, Cityshark II, was used with six three-component velocimeters attached (Lennartz 5 sec sensors). Three circles of different apertures were implemented on each site and a recording of 30 minutes to 1 hour was established depending on the aperture of the array. Long recordings were used for larger apertures and short recordings for smaller apertures. One station was located in the center of the site and the other five at approximately 72 degrees angles between them, depending on the building environment and nearby local sources of each site.

The aperture of each circle was selected based on the fundamental frequency at each site, from earthquake or/and individual noise recordings, and known shear wave velocity information up to a depth of at least 40 meters from Cross Hole data. An example of geometry adopted for station KOR1 is presented in Figure 2.

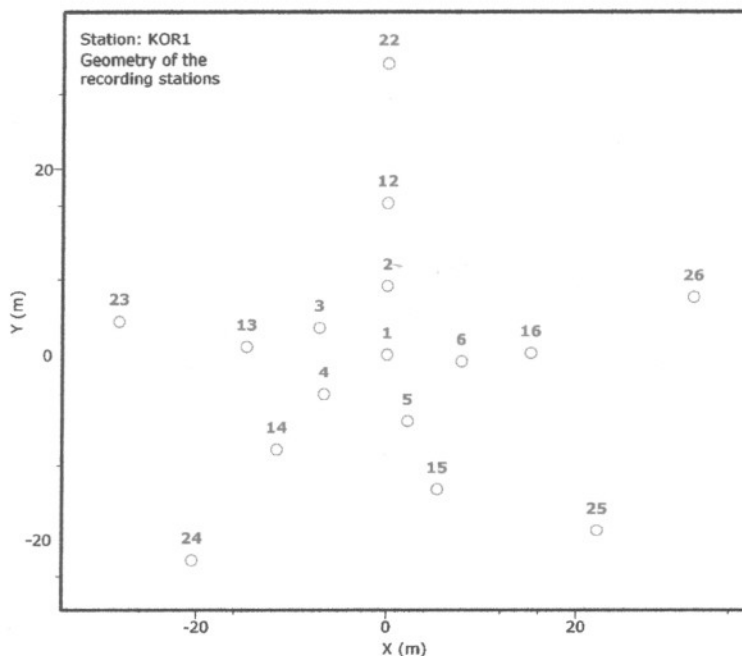


Figure 2. Geometry adopted in the field for microtremor array measurements for the site of KOR1. (1 central station, 2-6 inner circle, 12-16 middle circle, 22-26 outer circle)

3. Processing of Data

To homogeneously process earthquake data and calculate the receiver function (RF), the JSESAME software modules (SESAME European project, 2004a, 2004b) was applied. The entire recording length was taken, ranging from about 10sec to 40sec (Theodulidis et al., 2006).

The following steps were applied to all data used: (a) offset correction, (b) computation of Fourier spectra in all three components (E-W, N-S, UP), (c) application of a cosine taper, (d) smoothing of the Fourier amplitude spectra by a Konno-Ohmachi algorithm (Konno and Ohmachi, 1998). Data analysis was focused in the frequency range between 0.2 and 20 Hz. For each discrete frequency point the horizontal recording spectrum was divided by the vertical one, separately for both horizontal components. Thus, a common procedure was implemented so that any similarities or differences observed could be attributed to factors other than data processing itself.

Fundamental frequency, f_0 , of the RF spectral ratio was visually selected. For the examined stations two rough categories of sites with respect to f_0 , are observed. One including the stations Korinthos, Lefkas, Patra with f_0 equal or higher than 3.0Hz and another the stations Aigio, Vartholomio, Pargos with f_0 lower than 2.0Hz.

Before the processing of the array data, H/V calculations were implemented for all stations of each site as individual recordings in order to estimate a prominent peak corresponding to the fundamental frequency. The same computational parameters were used for H/V calculations for all stations by the SES-ARRAY software (Wathelet et al.,

2005). Using an anti-trigger module of the software along the recorded traces, the stable windows of the signal are detected automatically with the following parameters: Window length: 30 seconds, STA : 1.5 second, LTA : 30.0 seconds, Anti-trigger threshold : 0.3 - 2.0. Similar procedure to that used for earthquake data were applied to ambient noise measurement for the calculations of the fundamental frequency.

Data were processed using mostly the Conventional F-K (CVFK) technique and for some sites the Modified SPAC (MSPAC). The CVFK estimates (Kvaerna and Ringdahl, 1986), in sliding time window manner and narrow frequency bands around a center frequency, the parameters of propagation (direction and slowness) of the most coherent plane wave arrival. A grid search over the wavenumber plane is performed for each frequency in order to calculate the dispersion curve. The SPatial AutoCorrelation (SPAC) method is based on the precondition of a stochastic wavefield that is stationary in both time and space (Aki, 1957). Bettig et al. (2003) suggested a modification of Aki's original SPAC formula (MSPAC), which allows applying the spatial autocorrelation method for non-complete circular array configurations. The modification applied concerns the calculation of the averaged spatial autocorrelation coefficients from station pairs taken from rings of finite thickness instead of a fixed radius that is difficult to be implemented in a building environment.

Depending on the geometry of each circle the theoretical response was calculated in order to define the limitations of resolution and aliasing on the dispersion curve (DC) calculation. An example is presented in Figure 3 where the theoretical response of the inner array (radius of 7.5 m) is shown. On the Frequency/Slowness plot the k_{\min} and k_{\max} limits are calculated in order to approximately define the boundaries of the DC to be used from each array data set. An attempt to calculate the DC down to the f_0 resulted from the H/V of individual noise measurements or earthquake data. However, this was not possible in most of the sites since the building environment did not allow having very big apertures. In Figure 4 the DC calculated using the CVFK method for the middle circle for site KOR1, is presented. The theoretical response, corresponding to the middle circle, based on the geometry adopted is also shown.

4. Inversion of Dispersion Curve and Autocorrelation Data

The inversion code implemented from Wathelet et al., (2004) was used, which employs the neighborhood algorithm (Sambridge, 1999a, 1999b), in order to calculate shear wave velocity models from the DC data. Different attempts were evaluated for two, three, and four layers models in order to achieve the lowest misfit. Also, two layer models with the first layer consisting of five sub-layers following a power law were estimated. In Figure 5 the resulted three layer models are shown as calculated from the inversion of the DC data resulted from applying the CVFK method to the microtremor array data of station VAR1.

Direct inversion of autocorrelation curves as resulted from applying MSPAC in the recorded data was employed using the implementation of Wathlet et al., (2005). The results of the inversion for station VAR1 for a three layers model are presented in Figure 6. The autocorrelation curves are presented in the lower part. The grey dots correspond to the results after the processing and the colored curves correspond to the resulted models after the inversion. The resulted models along with the shear wave velocity profile from the CH data are also presented (upper left part). On the upper right hand side the DC's from the resulted models (color lines), the DC from the resulted model of the CH data and the DC from the processing of the data with the CVFK method, are shown.

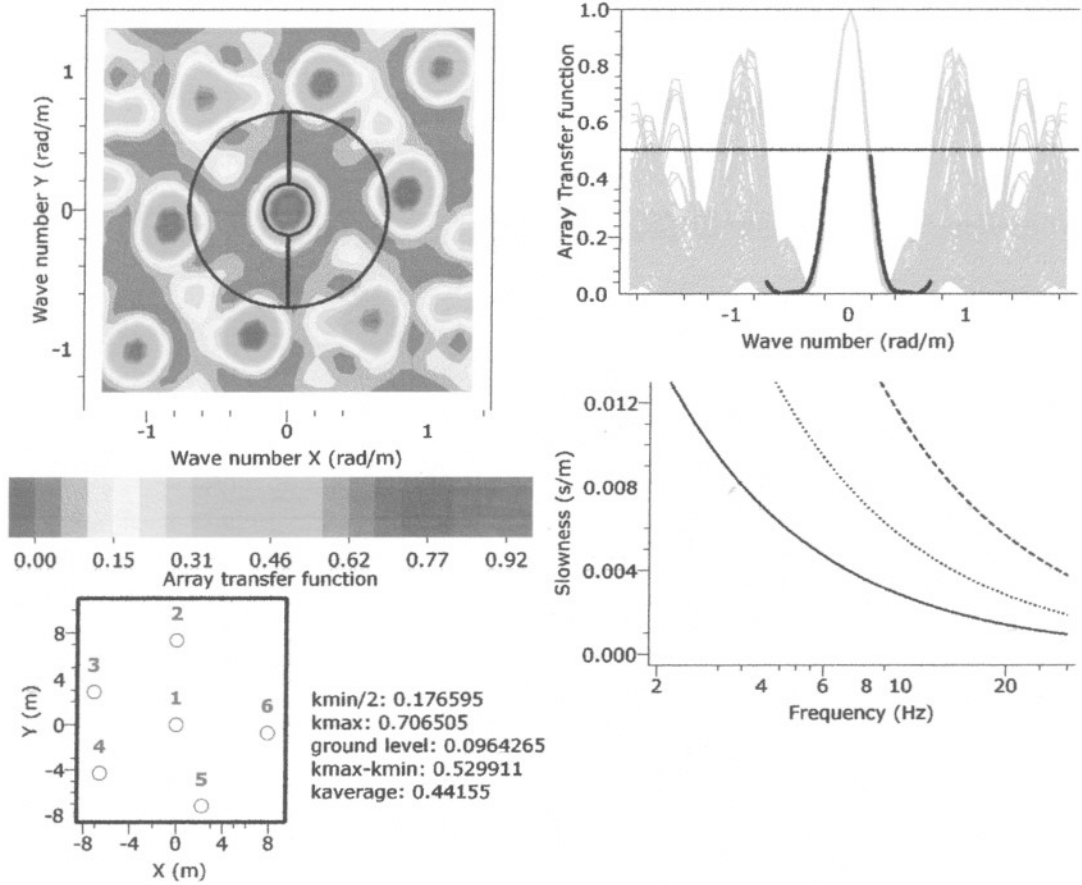


Figure 3. Theoretical Response of the Geometry of the Inner Circle for site KOR1

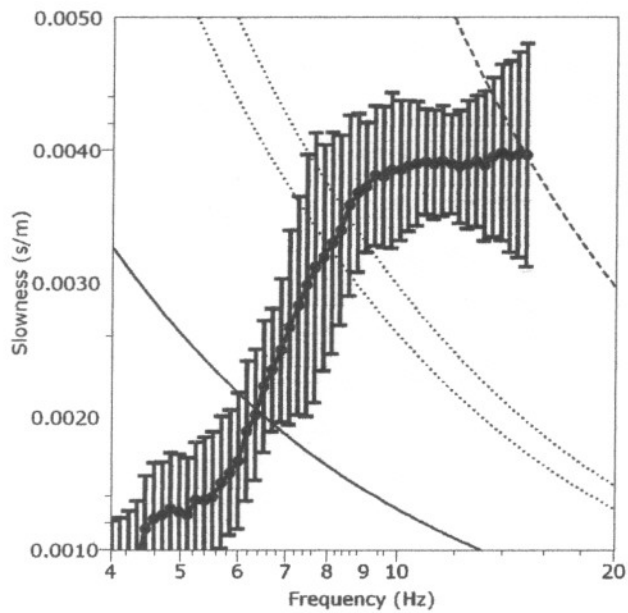


Figure 4. Dispersion curve calculation of the middle circle using CVFK (black dots) with the k_{min} (continuous line) and k_{max} (dashed line) limits plotted from the theoretical response calculation (KOR1).

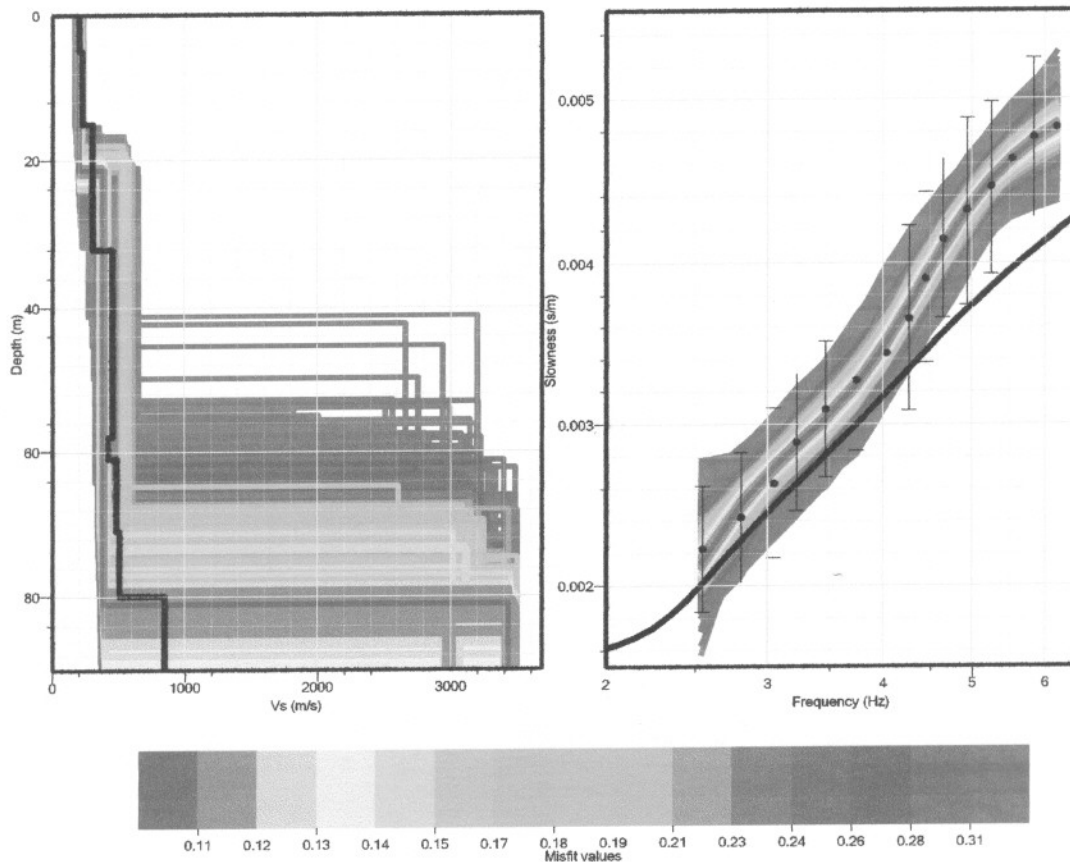


Figure 5. Resulted shear wave velocity model of three layers (left part) resulted from the inversion of the DC (black dots) information (right part). The shear wave velocity model from CH data and its respective DC is also presented with continuous black line (Vartholomio).

5. Discussion

In order to check the subjectivism of calculating shear wave velocity models using the same data set of array data and the same tools, two different teams of people were structured in order to follow a common procedure and check the coherency of their results, presented on Table I. On the first column the name of the site is given, following is the processing method used and the frequency band for which processing was established. On the fourth column is the parameter space used for the inversion (2l: two layers model, 2l grad: two layers model with the first layer consisting of five sub-layers that follow a power-law, 3l: three layers model, 3l-2LVL: three layers model with the second one allowing to be a low velocity layer), and following is the shear wave velocity of the first layer (V_{s_0}) preceded by the values of V_{s_0} corresponding to resulted models covering $\pm 50\%$ of the standard deviation of the dispersion curve or autocorrelation data. On columns 8-12 different statistical parameters are calculated corresponding to the mean values of V_{s_0} , $-V_{s_0}$, $+V_{s_0}$, and the limit of the shear wave velocity of the first layer in percentage of V_{s_0} , followed with the spread of data, the depth of the first layer [D_{s_0} (D_{array})] and the depth to the seismic bedrock [D_{s_1} (D_{array})]. The above information described is presented for both teams (TEAM A – orange color, TEAM B blue color on Table I). Following, the fundamental frequency ($f(hv)_1$) from H/V of ambient noise data and from earthquake recordings ($f(hv)_2$) are given when this information exists. For each team the

$h_{\min 1}$ ($D_{HVnoise}$) and $h_{\min 2}$ ($D_{HVe q}$) was calculated based on V_{s0} and the fundamental frequencies calculated before based on the formula $h_{\min} = V_{s0} / 4f(hv)$. This calculation was implemented for correlating h_{\min} with D_{s0} or D_{s1} calculated through the inversion. Finally, the coherence between the array results and Cross Hole results for V_{s0} and D_{s0} or D_{s1} are presented for each team.

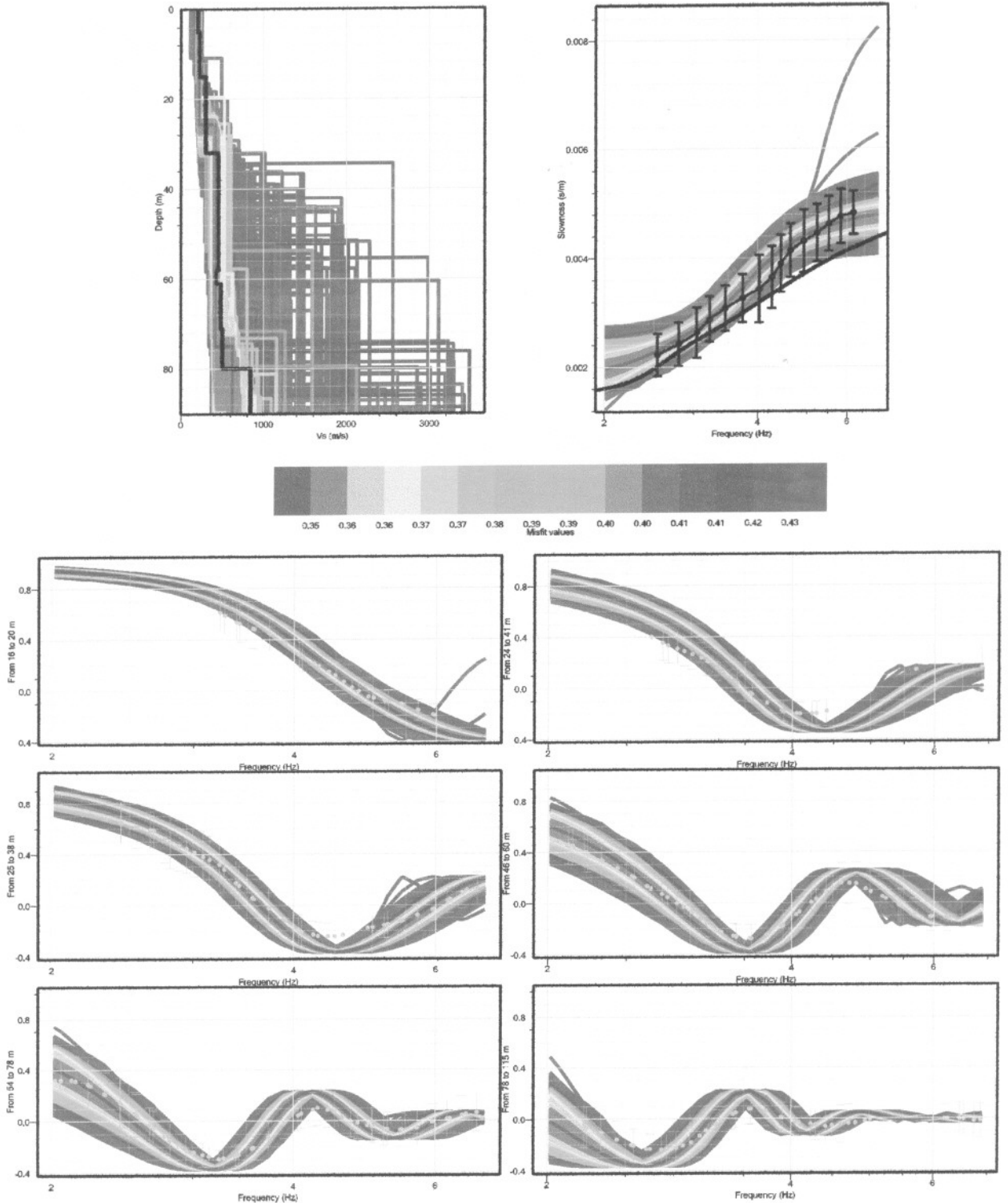


Figure 6. Resulted shear wave velocity model (upper left) from the inversion of the autocorrelation curves (lower part). The shear wave velocity model from CH data and its respective DC is also presented with continuous black line. The DC from the CVFK analysis is

also given (upper right),(Vartholomio).

There is a good correlation of $h_{\min 1,2}$ and D_{s_0} for sites Aigio, Korinthos, Lefkas, Vartholomio and with D_{s_1} for Pirgos. Additionally, there is a good correlation on V_{s_0} between array and CH shear wave velocities for Aigio, Korinthos, Lefkas, Vartholomio and Patras (only for the four layer models with a low velocity zone on the third layer). Finally concerning the correlation of D_{s_0} and D_{s_1} there is a high dependence on the parameter space used (two, three layer models) and differs from site to site if it is high with D_{s_0} or D_{s_1} .

6. Conclusions

The application of array microtremor data in six sites of the National Strong Motion Network has been evaluated through this work and its correlation with cross-hole results and H/V spectral ratio results from earthquake data.

Two processing methods have been applied to array data, CVFK and MSPAC, and further inversion of data showed that both methods could reveal satisfactorily shear wave velocity of the first layer (V_{s_0}) in most sites. However, when comparing the depth of the first layer (D_{s_0}) or the depth of the seismic bedrock (D_{s_1}) with the cross-hole results coherence is of medium quality showing no processing method dependence but site and parameter space (number of layer) dependence.

The depth of the first layer matches very well the one calculated using V_{s_0} and the fundamental frequency considered from H/V spectral ratios of ambient noise and earthquake data ($f(hv_1)$ $f(hv_2)$) (Table I).

This is a preliminary effort and certainly it is necessary to further check the validity of array microtremor method with other geophysical methods as well in order to use it for site characterization.

7. Acknowledgments

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